

## Detectability of CO<sub>2</sub> flux signals by a space-based lidar mission

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## Abstract

Satellite observations of carbon dioxide (CO<sub>2</sub>) offer novel and distinctive opportunities for improving our quantitative understanding of the carbon cycle. Prospective observations include those from space-based lidar such as the Active Sensing of CO<sub>2</sub> Emissions over Nights, Days, and Seasons (ASCENDS) mission. Here we explore the ability of such a mission to detect regional changes in CO<sub>2</sub> fluxes. We investigate these using three prototypical case studies, namely the thawing of permafrost in the Northern High Latitudes, the shifting of fossil fuel emissions from Europe to China, and changes in the source/sink characteristics of the Southern Ocean. These three scenarios were used to design signal detection studies to investigate the ability to detect the unfolding of these scenarios compared to a baseline scenario. Results indicate that the ASCENDS mission could detect the types of signals investigated in this study, with the caveat that the study is based on some simplifying assumptions. The permafrost thawing flux perturbation is readily detectable at a high level of significance. The fossil fuel emission detectability is directly related to the strength of the signal and the level of measurement noise. For a nominal (lower) fossil fuel emission signal, only the idealized noise-free instrument test case produces a clearly detectable signal, while experiments with more realistic noise levels capture the signal only in the higher (exaggerated) signal case. For the Southern Ocean scenario, differences due to the natural variability in the ENSO climatic mode are primarily detectable as a zonal increase.

## 1 Introduction

Satellite observations of carbon dioxide (CO<sub>2</sub>) offer novel and distinctive opportunities for improving our quantitative understanding of the carbon cycle, which is an important scientific and societal challenge with anthropogenic CO<sub>2</sub> emissions still on the rise. Prospective new observations include those from space-based lidar such as the Active Sensing of CO<sub>2</sub> Emissions over Nights, Days, and Seasons (ASCENDS) mission, which is proposed in "Earth Science and Applications from Space: National Imperatives for the Next Decade" [*National Research Council, 2007*] (henceforth referred to as the decadal survey). Notable features of this mission include its ability to sample at night and at high latitudes. These conditions are prohibitive to passive missions, such as the Greenhouse gases Observing SATellite (GOSAT) [e.g. *Kuze et al., 2009; Yokota et al., 2009*] and the Orbiting Carbon Observatory-2 (OCO-2) missions [e.g. *Crisp et al. 2004*], due to their reliance on reflected sunlight. The lidar measurement technique proposed for the ASCENDS mission further enables observing through some clouds and aerosols [*Ehret et al., 2008*], which also represent impediments and potential sources of bias for passive missions [e.g., *Mao and Kawa, 2004*]. Extensive instrument design research and development is ongoing, and proof of concept and validation studies indicate that ASCENDS will be able to provide high-precision, unbiased observations with improved spatial coverage compared to passive missions [e.g. *Spiers et al., 2011; Abshire et al., 2010; Kawa et al., 2010*].

The primary goals of the ASCENDS mission are to address open questions in carbon cycle science that focus on the identification of changing source/sink characteristics that are difficult to observe using other current or anticipated observations. These goals were first articulated in the decadal survey [*National Research Council, 2007*] and later refined in an ASCENDS mission NASA Science Definition and Planning Workshop [*ASCENDS Workshop Steering Committee,*

2008]. They include detecting changes in the northern high latitude sources and sinks, detecting changes in Southern Ocean source/sink characteristics, constraining anthropogenic CO<sub>2</sub> emissions, and increasing our understanding of biospheric carbon dynamics by differentiating photosynthetic and respiration fluxes [ASCENDS Workshop Steering Committee, 2008]. CO<sub>2</sub> fluxes in the northern high latitudes and in the Southern Ocean may change substantially as climate evolves, for example, and it is crucial to detect and attribute such changes quickly as they could lead to large increases in atmospheric CO<sub>2</sub> concentrations and subsequent shifts in climate dynamics [e.g. Canadell et al., 2010].

Guided by these stated goals, this study explores the extent to which a space-based lidar mission, using the ASCENDS mission concept as a guideline, can indeed contribute to these pertinent carbon cycle science questions. We specifically focus on the ability of such a mission to detect regional changes in fossil fuel emissions, high latitude CO<sub>2</sub> fluxes, and CO<sub>2</sub> fluxes in the Southern Ocean. We investigate these using three prototypical case studies, namely the thawing of permafrost in the Northern High Latitudes, the shifting of fossil fuel emissions from Europe to the Peoples Republic of China (China), and changes in the source/sink characteristics of the Southern Ocean related to the El Nino Southern Oscillation (ENSO). Realistic flux scenarios are defined for each of these prototypical case studies, within the anticipated time frame of the ASCENDS mission (i.e., the early to mid-2020s). These flux scenarios, combined with a common set of baseline fluxes, form the basis of the presented analysis.

One can view the experimental setup as a hypothesis testing setup to answer the question if, and how, the CO<sub>2</sub> concentration fields resulting from the baseline and perturbation fluxes, as observed by an ASCENDS-like mission, are distinguishable. To that end, the three scenarios described above are used in Observing System Simulations Experiments (OSSEs) to investigate

whether an ASCENDS-like mission will have the ability to identify the changes in atmospheric CO<sub>2</sub> distributions associated with the changes in fluxes represented in each scenario. We apply the geostatistical mapping approach developed in *Hammerling et al.* [2012a,b] to generate global CO<sub>2</sub> maps based on ASCENDS-like sampling of the atmospheric CO<sub>2</sub> distribution resulting from each flux scenario, and characterize the time required to observe statistically significant changes in the inferred global CO<sub>2</sub> distribution, given varying assumptions about measurement uncertainty.

## **2 Model-Simulated Data**

The study is based on simulated data described below. The study period represents a full year of the expected ASCENDS mission data.

### **2.1 Baseline CO<sub>2</sub> Atmosphere**

We use the parameterized chemistry and transport model (PCTM) to produce a simulated distribution of atmospheric CO<sub>2</sub> variability in space and time [*Kawa et al.*, 2004], based on the baseline and perturbation scenarios. Model transport is driven by real-time analyzed meteorology from the GEOS-5 Modern-Era Retrospective Analysis for Research and Applications (MERRA) [*Rienecker et al.*, 2011] for 2007. CO<sub>2</sub> surface fluxes for the baseline run include terrestrial vegetation physiological processes and biomass burning from CASA-GFED3 [*Randerson et al.*, 1996; *van der Werf et al.*, 2010], seasonally-varying climatological ocean fluxes from Takahashi et al. [2002], and fossil fuel burning from the CDIAC database [*Andres et al.*, 2009]. CASA fluxes are driven by MERRA data, which results in meteorologically-driven correspondence in the synoptic variability in the surface fluxes and atmospheric transport. The monthly CASA fluxes are downscaled to 3-hourly fluxes in the

method of Olsen and Randerson [2004] as described by e.g. Chatterjee et al. [2012] and Shiga et al. [2013]. The annual integral for the CASA fluxes is 1.53 Pg/yr representing a net source largely due to high respiration in 2007. The average yearly CASA flux for the period 1997 to 2012 is 0.133 Pg/yr. The CASA fluxes used in this study are available at the North American Carbon Data archive (<http://nacp-files.nacarbon.org/nacp-kawa-01/>). PCTM CO<sub>2</sub> output has been extensively compared to in situ and remote sensing observations at a wide variety of sites, and in most cases the model simulates diurnal to synoptic to seasonal variability with a high degree of fidelity [e.g. *Law et al.*, 2008a; *Parazoo et al.*, 2008; *Bian et al.*, 2006; *Kawa et al.*, 2004]. For the simulations here, the model is run on a  $1^{\circ} \times 1.25^{\circ}$  latitude/longitude grid with 56 vertical levels and hourly output. We use 2007 meteorological, cloud and aerosol, and reflectivity data for all components employed in the derivation of the simulated ASCENDS CO<sub>2</sub> observations.

## **2.2 Perturbation flux scenarios**

Three case studies are developed based on areas of interest within carbon cycle science that are directly relevant to the ASCENDS mission goals, namely the detection of regional changes in fossil fuel emissions, high latitude CO<sub>2</sub> fluxes, and changes in CO<sub>2</sub> fluxes in the Southern Ocean. They represent quantitatively plausible scenarios of changes in carbon fluxes, henceforth referred to as perturbation flux scenarios, that could occur by the early to mid-2020s, the planned launch timeframe for ASCENDS. These scenarios are used as prototypical examples of flux patterns that give rise to the types of signals the ASCENDS mission endeavors to detect. The perturbation fluxes are added to the baseline fluxes within the PCTM modeling framework described in section 2.1 to produce the perturbation CO<sub>2</sub> atmospheres henceforth referred to as perturbation runs.

### 2.2.1 Permafrost carbon release

The permafrost carbon feedback is an amplification of surface warming due to the release of CO<sub>2</sub> and methane from thawing permafrost [Zimov *et al.* 2006]. Permafrost soils in the high northern latitudes contain approximately 1700 Gt of carbon in the form of frozen organic matter [Tarnocai *et al.* 2009]. Permafrost is perennially frozen ground remaining at or below 0°C for at least two consecutive years [Brown *et al.* 1998] occupying about 24% of the exposed land area in the Northern Hemisphere [Zhang *et al.* 1999]. As temperatures increase in the future and the permafrost thaws, the organic material will also thaw and begin to decay, releasing CO<sub>2</sub> and methane into the atmosphere. CO<sub>2</sub> and methane emissions from thawing permafrost will amplify the warming due to anthropogenic greenhouse gas emissions [Zimov *et al.* 2006].

The permafrost carbon emissions scenario applied here uses projections of CO<sub>2</sub> fluxes from thawing permafrost from Schaefer *et al.* [2011]. Schaefer *et al.* [2011] use the Simple Biosphere/Carnegie-Ames-Stanford Approach (SiBCASA) land surface model [Schaefer *et al.*, 2008] driven by output from several General Circulation Models for the A1B scenario from the IPCC Fourth Assessment report [Lemke *et al.*, 2007]. The fluxes are an ensemble mean of 18 projections from 2002 through 2200. We ran the PCTM model with the extracted fluxes for 2020 to 2022 and used the 2022 fluxes as perturbation fluxes. The annual integrals for the permafrost perturbation fluxes are 0.613 PgC/yr, 0.641 PgC/yr and 0.752 PgC/yr for 2020 to 2022, respectively.

The flux perturbations are concentrated in areas of discontinuous permafrost along the southern margins of permafrost regions (Figure 1). In discontinuous permafrost regions, north-facing slopes might form permafrost, while south-facing slopes may not. Permafrost temperatures hover just below freezing, making these regions vulnerable to thaw for small

increases in atmospheric temperature. Normally, the surface soils in the active layer thaw each summer and refreeze each winter. However, as temperatures increase, the thaw depth becomes too deep to refreeze in the winter, forming a talik or layer of unfrozen ground above the permafrost. The talik allows microbial decay to continue during winter when the surface soils are frozen, resulting in year-round fluxes that peak in summer when soil temperatures are highest (see Figure A1 in supplementary material).

The CO<sub>2</sub> concentrations of the baseline run were mean-adjusted to match the annual mean of the perturbation run by applying a multiplicative adjustment. This adjustment preserves the spatial patterns of the baseline run, while the global difference in concentrations between the baseline and perturbation run is zero, so effectively a global flux-neutral scenario. This has been done to focus this study on the detectability of changes in spatial patterns rather than detecting the mean interannual increase in CO<sub>2</sub> concentrations that results from the strictly positive perturbation fluxes over the two years of model spin-up and the investigated year.

### **2.2.2 Shift in fossil fuel emissions**

The fossil fuel flux perturbation scenario consists of a shift of fossil fuel emissions from Europe to China; a shift that is in directional agreement with recent trends in these regions. Fossil fuel emissions from China have increased rapidly over the last decades and China is now largest emitter of CO<sub>2</sub> worldwide [Olivier *et al.*, 2012; Peters *et al.*, 2011]. By comparison, fossil fuel emissions from Europe decreased 3% in 2011 relative to 2010 with an overall decline over the last two decades [Olivier *et al.*, 2012]. We used two magnitudes of emission shift, from here on referred to as the “lower” and “higher” signal, representing two points on a continuum of possible emission changes around the year 2022.



The lower signal represents a 20% decrease of European emissions, with a 12% increase in China (Figure 2) that exactly offsets the European decrease. The higher signal includes a 50% decrease of emissions in Europe with a corresponding 30% increase in China (Figure 2), and is used for illustration purposes only, as a decrease of this size is not expected in Europe within a decade. All the percentage changes are in reference to 2007 emission levels, based on the v2011 2007 fossil fuel emissions from the CDIAC data base [Andres *et al.*, 2011]. The annual flux integrals for the lower and higher signals are 0.228 PgC/yr and 0.571 PgC/yr, respectively. We use these two shift settings as examples to draw broader conclusions on the detectability of these types of signals as characterized by their the spatial and temporal patterns and their magnitudes.

The flux perturbations are globally flux neutral, in that European fossil fuel fluxes are reduced by a set percentage in each month and the total emissions from China are increased by the same mass amount. The decrease and increase is conducted proportionally to the existing spatial pattern of the fluxes for each month, thereby preserving the spatial and temporal patterns within the European and Chinese fluxes (Figures A2 and A3 in supplementary material). The fluxes vary relatively little from month to month, on average +/- 15%. Overall, the signal to be detected is a difference in the spatial distribution of CO<sub>2</sub> concentrations, with the global mean remaining unchanged.

### **2.2.3 Changes in Southern Ocean fluxes**

The Southern Ocean is of special interest to carbon cycle science, because its CO<sub>2</sub> fluxes are highly uncertain [Gruber *et al.*, 2009], it is a region with apparent high sensitivity to climate change [Le Quéré *et al.*, 2009], and this sensitivity has implications for the region's future as a carbon sink because half of the ocean uptake of anthropogenic CO<sub>2</sub> is estimated to occur there [e.g. Le Quéré *et al.*, 2009; Meredith *et al.*, 2012]. There is disagreement on the current and

future trend of the carbon flux in the Southern Ocean [*Le Quéré et al.*, 2009; *Law et al.*, 2008b]. The Southern Ocean is also a very sparsely sampled region, where the ability of the ASCENDS mission to observe at high latitudes could provide valuable insights.

Variations in climate modes are a key driver of interannual variability in ocean carbon exchange [e.g. *Field et al.*, 2007]. Here we evaluate the extent to which interannual variability due to variations in climatic modes, such as the El Nino Southern Oscillation (ENSO), can be detected as a reference for addressing potential changes in the sink/source characteristics of the Southern Ocean using satellite observations. In other words, we use ENSO-related variability as a prototypical example of the scale of variability to detect. To that end, the years 1977 and 1979 were chosen as examples of estimated flux patterns, as they represent large differences in ocean fluxes due to variations in climatic modes.

The Southern ocean fluxes for this scenario are based on a hind cast simulation of the Community Climate System Model (CCSM) Ocean Biogeochemical Elemental Cycle model as described by Doney et al. [2009]. The fluxes were obtained at  $1^{\circ} \times 1^{\circ}$  spatial and monthly temporal resolution. The monthly difference between the Southern ocean flux anomaly for 1977 and 1979 is used as the perturbation flux for this scenario. Figure 3a and 3c show the average flux perturbation for April through June and the full year, respectively. A year-round time series of these monthly perturbation fluxes is shown in Figure A4 (supplementary material). The magnitude of the perturbation fluxes (1977: 0.186 PgC/yr, 1979: -0.176 PgC/yr) is low relative to the other two case studies. In contrast to the other two experiments, the sign of the perturbation flux also varies by month and spatially within the region.

### 2.3 Simulated ASCENDS CO<sub>2</sub> observations

Anticipated ASCENDS sampling and random measurement error characteristics are derived from model output and observations in a method similar to that of Kawa et al. [2010] and Kiemle et al. [2014]. The Cloud-Aerosol Lidar and Infrared Pathfinder Satellite Observation (CALIPSO) orbital track is used to simulate the expected ASCENDS sampling. Synthetic observations are sampled from model output at the nearest time to the satellite over-flight, and interpolated in space to the CALIPSO sample locations. A vertical weighting function, appropriate to an ASCENDS laser instrument operating at a wavelength near 1.57  $\mu\text{m}$ , is applied to the model pseudo-data profile to produce column average mixing ratio values [Ehret et al., 2008]. We consider only random errors due to photon counting. Potential bias errors [e.g. Baker et al., 2010], which could significantly complicate the analysis if correlated with geophysical variables of interest (e.g., land/ocean or vegetation cover), are not included.

CALIPSO measurements of total cloud and aerosol optical depth (OD) are used to calculate the ASCENDS laser attenuation. CALIPSO OD data are reported every 5 km (corresponding to every 0.7435 s) along track and this forms the basic ASCENDS sample set. Surface lidar backscatter ( $\beta$ ), also needed for error estimation, follows from MODIS measured spectral reflectance over land and the glint formulation of Hu et al. [2008] over water using daily MERRA 10-m wind speeds. Surface reflectivity over land is interpolated from MODIS (Terra + Aqua) 5-km 16-day composite nadir BRDF-adjusted reflectance data ( $\alpha$ ) at 1.64  $\mu\text{m}$  (band 6), which are available every 8 days [Schaaf et al., 2002]. Land reflectance is scaled by a factor of 1.23 to account for the land ‘hot spot’ backscatter effect [Disney et al., 2009], i.e.,  $\beta \text{ (sr}^{-1}\text{)} = 1.23 \alpha/\pi$ . Backscatter values of 0.08  $\text{sr}^{-1}$  and 0.01  $\text{sr}^{-1}$  are used to fill missing areas of MODIS data

235 over land and over snow/ice, respectively, where ice and snow cover is determined from  
236 MERRA data.

237 In order to make our study method applicable for a range of possible CO<sub>2</sub> laser sounder  
238 instrument implementations, we scale the errors globally to a nominal error value for clear-air  
239 conditions at Railroad Valley, NV ( $\beta = 0.176$ ,  $T = 1$ ) and a 10-s (67.2 km) sample integration.  
240 Thus, a given instrument model can be characterized by its random error at the Railroad Valley  
241 reference point and the global distribution of errors estimated from OD and  $\beta$ . The individual  
242 sounding errors at the 5 km CALIPSO resolution are calculated using:

$$\sigma_{5\text{km}} = \frac{3.667 * \sigma_{\text{ref}}}{\left(\frac{\beta * T^2 * sdf}{0.176}\right)^{0.5}}, \quad (1)$$

243 where  $\sigma_{\text{ref}}$  is the 10-s reference instrument random error (standard deviation) at Rail Road  
244 Valley,  $T$  the transmittance,  $sdf$  the surface detection frequency, and 0.176 is the Rail Road  
245 Valley backscatter reference value at 1.57  $\mu\text{m}$ , which corresponds to one of the potential  
246 ASCENDS instrument designs [Abshire *et al.*, 2010]. The transmittance is calculated from the  
247 CALIPSO (OD) using  $T = e^{-OD}$ .

248 Soundings with an optical depth greater than 0.3 or where the surface detection frequency  
249 equals zero are filtered out and considered 'not retrieved'. The surface detection frequency  
250 equals zero when none of the 1-km averaged CALIPSO samples in a 5-km average can see a  
251 ground return, i.e., the clouds/aerosol were too thick to get a return from the ground. For this  
252 study we a 10-s along-track average as our pseudo-data measurement granule [Kawa *et al.*,  
253 2010]. Using this setup, the maximum number of soundings constituting one observation is 14.  
254 The 10-s observation error variances are then calculated by averaging the 5-km error variances

within each 10-s time interval and dividing this average by the number of retrieved soundings. This setup implies the assumption that retrieval errors between individual soundings are spatially and temporally uncorrelated. We include three measurement noise settings in the study. A no-measurement noise setting for reference purposes, and medium and high noise settings, which use Rail Road Valley 10-s reference instrument random errors ( $\sigma_{\text{ref}}$ ) of 0.5 and 1 ppm, respectively. Once the measurement error variance has been determined for each location following the procedure described above, a random sample from a normal distribution with that variance is drawn and added to the PCTM model CO<sub>2</sub> value to define a pseudo-data observation. The global mean errors ( $\sigma_{\text{obs}}$ ) are 2.1 and 4.2 ppm, respectively, for the medium and high noise settings. Figure 4b provides an example of four days of global observations. Different random seed numbers are used for the errors in the baseline and the perturbation runs.

## 3 Methods

### 3.1 Mapping approach

We use a geostatistical mapping approach [Hammerling *et al.*, 2012a,b] to create contiguous interpolated maps, i.e. global mapped ("Level 3") products, for the comparison. Satellite CO<sub>2</sub> observations contain large gaps and high measurement errors such that meaningful spatially-comprehensive comparisons at synoptic timescales are often precluded using the observations directly. Using gap-filled products makes it possible to conduct synoptic, global comparisons. The approach presented in Hammerling *et al.* [2012a,b] also yields spatially-explicit uncertainties (eq. 7 in Hammerling *et al.* [2012a]) of the mapped products. These may be lower than the uncertainties of the individual observations in areas where the correlation with nearby observations can be leveraged, which in turn can facilitate signal detection.

The applied mapping methodology yields global mapped CO<sub>2</sub> concentrations with uncertainty measures without invoking assumptions about fluxes or atmospheric transport. The method leverages the spatial correlation in the atmospheric CO<sub>2</sub> concentration field, parameterized as an exponential covariance function with spatially-varying variance and correlation range parameters using a moving-window circular domain of 2000 km. These parameters are estimated from the observations, and thus not imposed *a priori*. Methodological details are given in *Hammerling et al.* [2012a,b].

Specific to this study, we filter the pseudo-data observations to those with a measurement error standard deviation below a certain threshold. This is analogous to imposing a quality criterion when delivering remote sensing data instead of making all retrievals available. For the medium (high) measurement error setup this threshold is 1.5 (3.0) ppm. This choice represents a balance between spatial coverage and robustness of the covariance estimation procedure and was determined in a sensitivity analysis (results not shown). For the "no error" setup, which is only used as a theoretical best case, we use observations at the same locations as for the medium and high measurement setups, but without any noise added. We include this case to isolate any potential limitations of the methodology and the spatial coverage from those related to the instrument capabilities.

Mapping CO<sub>2</sub> satellite observations at synoptic time scales makes it possible to capture the dynamic behavior of CO<sub>2</sub> in the atmosphere [*Hammerling et al.*, 2012a, b]. Based on preliminary studies evaluating mapping performance for different time periods, 4-day periods were found to provide the best balance between ensuring good data coverage while also capturing synoptic behavior for ASCENDS-like observations. Figure 4 shows an example of a 4-day (August 1- 4 2007) period. The average modeled CO<sub>2</sub> distribution is shown for reference,

and only the observations are used in the subsequent mapping procedure. Each 4-day period is mapped independently from other 4-day periods and for the baseline and perturbation runs. For January, only six 4-day periods were mapped due to missing CALIPSO data; for all other months, seven 4-day periods were mapped for a total of 83 4-day maps for each of the baseline and perturbation cases. These mapped fields were then used as input data in the subsequent comparison analysis described in Section 3.2

### 3.2 Comparison approach

The detectability of a signal is assessed point-wise for each model grid cell by comparing the mapped concentrations from the baseline run and the perturbation run, and determining whether the observed differences exceed their associated uncertainties. The uncertainty of the difference between two mapped concentration fields, expressed as a variance, is the sum of the estimation variances of the baseline,  $\sigma_{\hat{y}_{base}}^2$ , and the perturbation,  $\sigma_{\hat{y}_{per}}^2$ , mapped products:

$$\sigma_{diff}^2 = \sigma_{\hat{y}_{base}}^2 + \sigma_{\hat{y}_{per}}^2$$

For ease of interpretation and visualization purposes, the comparison results are binned by their relative uncertainties, where the absolute value of the difference exceeds one, two or three standard deviations, respectively, of the uncertainty of the difference.

Due to the measurement error added to the observations, together with the sparseness of the available observations, individual 4-day maps do not exhibit detectable differences in a statistical sense, and the question then becomes to identify a time period over which such 4-day maps must be averaged before a significant signal emerges. Under the assumption of temporal independence, the uncertainty (expressed as a variance) of the temporal mean is the mean

mapping variance of the individual periods divided by the number of periods. The assumption of temporal independence was evaluated by conducting temporal variogram analyses for sets of mapping errors at randomly selected locations (results not shown), and no compelling indication to contradict this assumption was found.

## **4 Results and Discussion**

On a high level, one can view the query of detecting atmospheric CO<sub>2</sub> concentration signals resulting from flux perturbations as two distinct, if connected, questions. The first question is how characteristics of the flux perturbations are translated to, and preserved in, the atmospheric CO<sub>2</sub> concentrations, i.e. what is the signature (or signal) of a set of flux perturbations of interest in the atmospheric CO<sub>2</sub> concentrations. The second question is how well a given observing system, in our case the ASCENDS mission, can capture the presence of this signal. Both of these aspects are discussed in the following sections, which are organized by the three investigated scenarios.

### **4.1 Detectability of permafrost carbon release**

A significant signal can be detected in the case of the anticipated permafrost carbon emissions (Figures 5 and A5). The challenge is in capturing longitudinal and latitudinal gradients, which can better attribute the increase to the permafrost region, as opposed to just detecting a zonal increase. While signal detection is not directly targeted at quantifying carbon fluxes, insights on the detectability of spatial gradients are highly relevant for studies targeting flux detections, e.g. atmospheric inverse modeling studies. With this in mind, a judicious choice of the temporal aggregation periods over which the comparisons are conducted is important.



Because of the seasonality of the fluxes in the permafrost carbon release scenario (Figure A1), the gradients in the atmospheric CO<sub>2</sub> distribution are most evident in the months following the start of the spring thaw. As a result, averaging over spring/summer months yields a clearer identification of the geographic origin of the signal relative to aggregating maps over the full year. While the concentration signal is highest around September (Figure A1), or even later in the year, when the active layer is deepest, the concentration signals indicative of the spatial pattern of the tundra fluxes are most distinct in the late spring/early summer months before the effects of atmospheric mixing take over. By August, atmospheric mixing, which occurs rapidly in the Arctic, causes the spatial signature of the tundra melting fluxes to be replaced by the dominant signal of a zonal increase. Some further evidence of this phenomenon can be observed by comparing Figures 1b and 1d: the 3-month signal retains more of the spatial characteristics, whereas the yearly signal represents a zonal increase where the elevated concentrations have spread towards the pole. This phenomenon is caused by the specific combination of the temporal pattern of the permafrost carbon release and rapid atmospheric mixing in the High Northern Latitudes.

Figures 5 and A5 show a summary of the detection results for the permafrost carbon release scenario. While the 3-months results feature comparatively more noise, the recognition of the spatial pattern in the significance plots is also improved. Even for the high noise scenario, the land origin of the signal is better seen in the 3-month maps relative to the yearly plots. The results for the different noise levels are as expected; lower noise provides a more accurate mapped concentration field (Figure A5). Overall, the permafrost CO<sub>2</sub> perturbation is detectable for both levels of measurement noise considered, and spatial gradients are best detected using two to three month aggregation periods in the late spring/early summer.

## 4.2 Detectability of shift in fossil fuel emissions

The examined fossil fuel emissions perturbations lead to a pronounced spatial signature that is localized over Europe and China (Figures 2c, g; 2d, h; A2; A3). This is in contrast to the other two experiments (see Figures 1d and 3d), where the detailed spatial signatures are largely lost and especially the yearly signals represent primarily zonal increases. In addition, the magnitude of the lower fossil fuel perturbation signal is very low, which, combined with its small spatial extent, renders the weak fossil fuel signal the most difficult to detect among the investigated scenarios. This exemplifies the challenge of detecting small and localized flux changes from satellite observations.

The highly localized nature of the signal over Europe and China suggests that changes in fluxes would be detectable and attributable to a given region, even if these fluxes were not offset by a corresponding shift in emissions within a similar latitudinal range. It is interesting to observe the different dispersion patterns of the European and Chinese emissions, especially when considering their latitudinal range. The effect on the atmospheric concentrations of the European emissions can be observed from equatorial Africa to the Arctic, whereas the range of the Chinese emissions is more limited to their originating latitudinal band (see Figure 2h).

Given the relative lack of seasonality in the fossil fuel perturbation scenarios, averaging over longer periods of time leads to better detectability (Figure 6). Although atmospheric transport clearly plays a role, the atmospheric signal remains indicative of the source region of the perturbation flux throughout the seasons. Figure 6h, for example, shows evidence that both the source and downwind regions of the emissions have a significant signature in the atmosphere.

The effect of varying measurement noise levels on the detectability is again as expected; increasing measurement noise leads to decreased significance in the results and requires in turn longer averaging periods. For the higher signal, all three noise levels capture the signal in the yearly results, which is not the case for the lower signal, where only the no error case clearly captures the signal (Figure A6). There is some evidence that a significant signal is detectable in the yearly medium and high error measurement noise cases (Figure 6), and given the nature of the signal discussed above, the signal is expected to appear more clearly when averaging over periods exceeding one year. Overall, these findings imply that ASCENDS can in principle detect anthropogenic signal components, but depending on the strength of the signal, detection might require multiple years. It is hence feasible that ASCENDS can serve to validate anthropogenic emission changes over the course of its mission, but is likely not ideal as the primary monitoring tool for such flux changes.

#### **4.3 Detectability of changes in Southern Ocean fluxes**

The detection of changes in the Southern Ocean source/sink characteristics is challenging as a result of a confluence of different factors. The overall magnitude of the signal in the Southern Oceans is rather weak, with the absolute value of the signal never exceeding 0.4 ppm in the column. In addition, this scenario involves sub-seasonal and sub-regional-scale flux variability that is superimposed on a seasonal pattern in the fluxes (Figure A4). Atmospheric mixing also plays a role insofar as it obscures the Southern Ocean as the origin of the signal, as was also observed in the permafrost carbon release scenario. However, applying the remedy of using a shorter averaging period before atmospheric mixing hides the origin of the signal is not as clear-cut for the Southern Ocean scenario, because the overall signal is weaker. Spatial gradients associated with the Southern Ocean flux perturbation are most evident in the spring and early

summer (Figure 3). Later in the year, although the concentration signal is stronger, the concentration increase has spread pole-ward and is less attributable to the Southern Ocean.

For all measurement noise setups, the yearly results clearly indicate a zonal increase in the High Southern Latitudes (Figures 7 and A8). However, it is less clear whether the pattern is indicative of the Southern Ocean being the source region within the zonal band. The spatial pattern of the 3-month results (Figures 7b) is more indicative of the Southern Ocean as the source region, but the significance levels are not very high. The most beneficial approach for the Southern Ocean scenario appears to be conducting analyses over periods of multiple lengths, and drawing conclusions from the joint picture emerging from these analyses. In summary, ASCENDS can detect a Southern Ocean signal representative of differences due to natural variability in the ENSO climatic mode. ASCENDS may provide a unique measurement view of these regions because the pervasive cloudiness and low sun angles present difficult conditions for passive satellite CO<sub>2</sub> sensors. Due to the low magnitude and small-scale variability within the fluxes giving rise to the signal, however, attributing the signal to specific ocean regions or biogeophysical processes will likely require additional corroborative information.

## **5 Conclusions**

This work assesses the degree to which ASCENDS, a planned lidar CO<sub>2</sub> observing satellite mission, can contribute to the detection of three types of CO<sub>2</sub> flux change scenarios relevant to global carbon cycle science: the release of carbon due to the thawing of permafrost in the Northern High Latitudes, the shifting of fossil fuel emissions from Europe to China, and ENSO-related changes in the source/sink characteristics in the Southern Ocean. These three scenarios were used to design OSSEs for signal detection studies to investigate if the ASCENDS mission

has the ability to detect the unfolding of these scenarios compared to a baseline scenario. Two different levels of measurement noise and a no measurement noise reference case were investigated.

This study is based on a number of simplifications. For each scenario, the only flux component that is varied is the flux component under investigation, while all other fluxes are fixed. In reality, many changes might occur simultaneously and the resulting CO<sub>2</sub> concentration signal patterns might overlap, which makes signal detection more challenging. We have introduced some additional variability by sampling and mapping the baseline concentration field rather than assuming a static baseline concentration field in the comparison procedure, however, that might not be equivalent to, for example, having misspecified biospheric fluxes. Such misspecifications could be aliased with the true signals and misleading signal patterns could occur. This could impact the conclusions of this study insofar that it would be more difficult to link detectable signals with the underlying change in fluxes.

The results indicate that the ASCENDS mission can in principle detect the types of signals investigated in this study. The permafrost thawing flux perturbation is readily detectable at a high level of significance. Spatial gradients, which are of great interest for process attribution, were best detected using two or three month aggregation periods in the late spring/early summer. For the Southern Ocean scenario, differences due to the natural variability in the ENSO climatic mode were primarily detectable as a zonal increase. The relative magnitude of the signal, however, is much smaller than the permafrost-thawing signal. Spatial and temporal high-frequency changes in the anomaly fluxes produce additional variability in the signal, making detection of more detailed gradients than a zonal increase challenging for the Southern Ocean

scenario. Conducting analyses over periods of varying lengths and analyzing them jointly provides a possible diagnostic strategy.

The fossil fuel emission detectability is directly related to the strength of the signal and the level of measurement noise. As is true for all scenarios, the effect of varying measurement noise levels is as expected: increasing measurement noise levels lead to decreased significance in the results and require in turn longer averaging periods. For the nominal (lower) fossil fuel emission signal, only the noise-free instrument test produces a clearly detectable signal, while all three noise levels capture the higher (exaggerated) signal case. The emergence of a detectable signal suggests that averaging over periods longer than the one-year period considered in this study would also render signals of the magnitude of the lower fossil fuel emission signal detectable.

All in all, the expected precision and sampling characteristics of ASCENDS promise to substantially enhance our ability to detect variations in CO<sub>2</sub> fluxes and to inform the mechanisms that control them. Future work includes comparing the signal detection performance of ASCENDS to passive sensors, which might be employed within the time frame of the ASCENDS mission. Additional future work entails a comprehensive study of the effect of uncertainties in fluxes other than those defining the signal on the detectability of the signal, for example, by using an ensemble of biospheric fluxes to vary the baseline fluxes.

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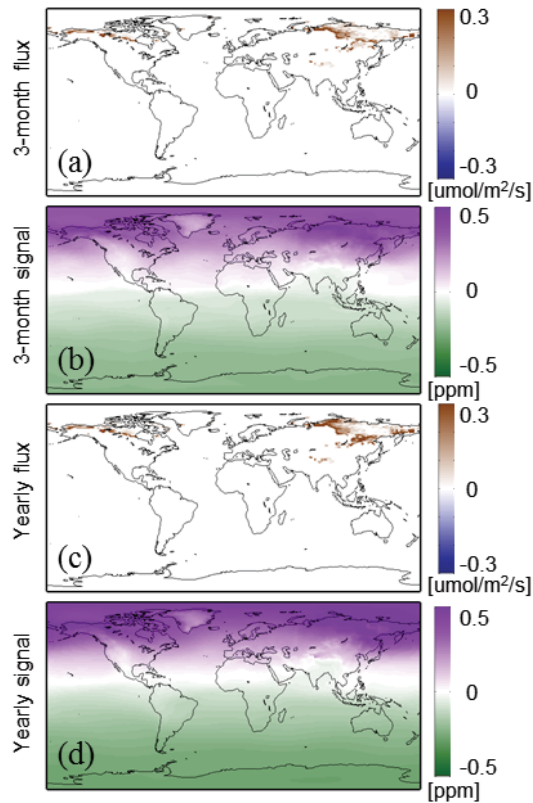
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618        Figure 1: Flux and CO<sub>2</sub> concentration for the permafrost carbon release experiment. (a) 3-  
619        month average CO<sub>2</sub> flux (“3-month flux”), (b) 3-month average CO<sub>2</sub> concentration (“3-month  
620        signal”), (c) yearly average CO<sub>2</sub> flux (“Yearly flux”), and (d) yearly average CO<sub>2</sub> concentration  
621        (“Yearly signal”). The 3-month period is May through July. The flux is modeled for 2022. The  
622        negative concentration values in the Southern hemisphere are a result of the global mean  
623        adjustment.

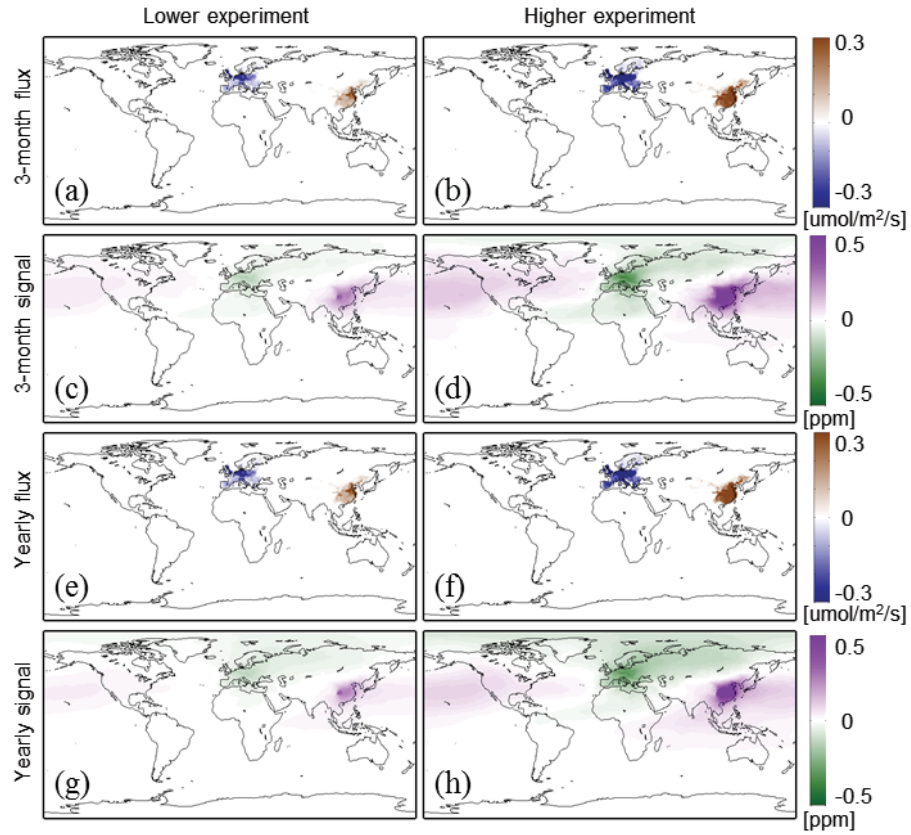
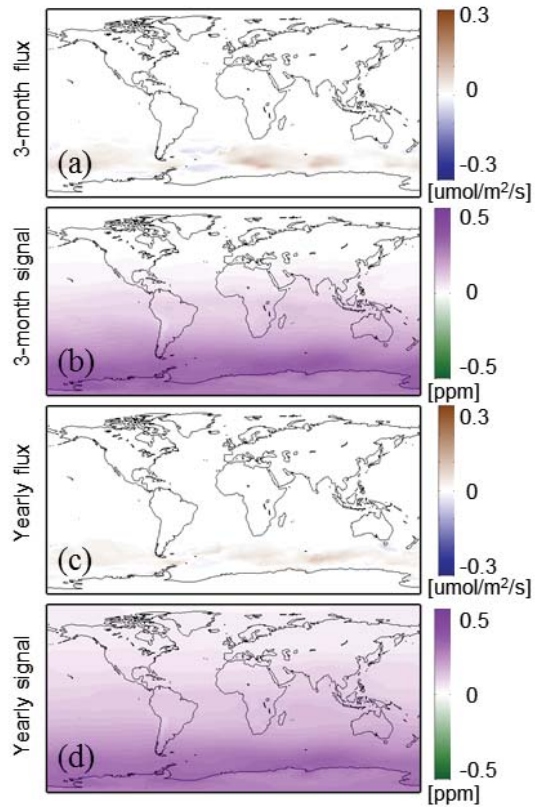


Figure 2: Flux and CO<sub>2</sub> concentration for the fossil fuel experiments. First row: 3-month average CO<sub>2</sub> flux (“3-month flux”). Second row: 3-month average CO<sub>2</sub> concentration (“3-month signal”). Third row: Yearly average CO<sub>2</sub> flux (“Yearly flux”). Fourth row: Yearly average CO<sub>2</sub> concentration (“Yearly signal”). The 3-month period is August through September.



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630 Figure 3: Flux and CO<sub>2</sub> concentration for the Southern Ocean experiment. (a) 3-month  
 631 average CO<sub>2</sub> flux (“3-month flux”), (b) 3-month average CO<sub>2</sub> concentration (“3-month signal”),  
 632 (c) yearly average CO<sub>2</sub> flux (“Yearly flux”) and (d) yearly average CO<sub>2</sub> concentration (“Yearly  
 633 signal”). The 3-month period is April through June.

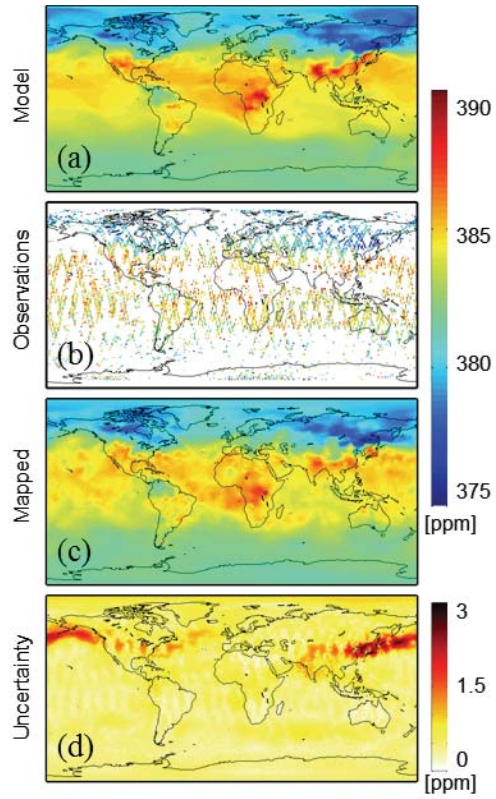


Figure 4: Mapping results for August 1-4 2007. (a) Modeled CO<sub>2</sub> concentrations (“Model”), (b) simulated ASCENDS observations (“Observations”), (c) mapped CO<sub>2</sub> concentrations (“Mapped”), and (d) mapping uncertainties (“Uncertainty”) expressed as a standard deviation.



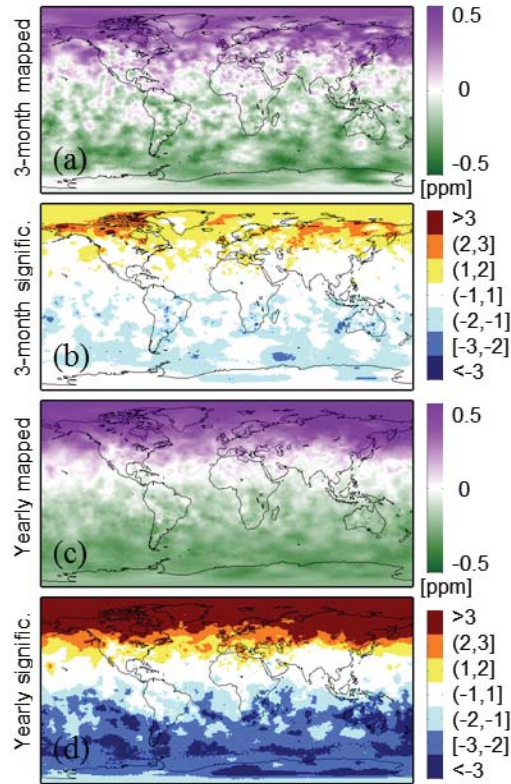


Figure 5: Results for the permafrost carbon release experiment for medium measurement noise. (a) 3-month mapped CO<sub>2</sub> signal (“3-month mapped”), (b) Significance of the 3-month mapped CO<sub>2</sub> signal (“3-month signific.”), (c) Yearly mapped CO<sub>2</sub> signal (“Yearly mapped”), and (d) Significance of the yearly mapped CO<sub>2</sub> signal (“Yearly signific.”). The mapped signal is the difference between the mapped perturbation CO<sub>2</sub> concentration and the mapped baseline CO<sub>2</sub> concentration. The significance is the mapped signal divided by the uncertainty of the mapped signal. The values are discretized for improved visualization. Yellow, orange and dark red (light, medium and dark blue) represent areas where the mapped perturbation concentration is larger (smaller) than the mapped baseline concentration by more than one, two or three standard deviations, respectively, of the uncertainty of the mapped signal. The 3-month period is May through July.



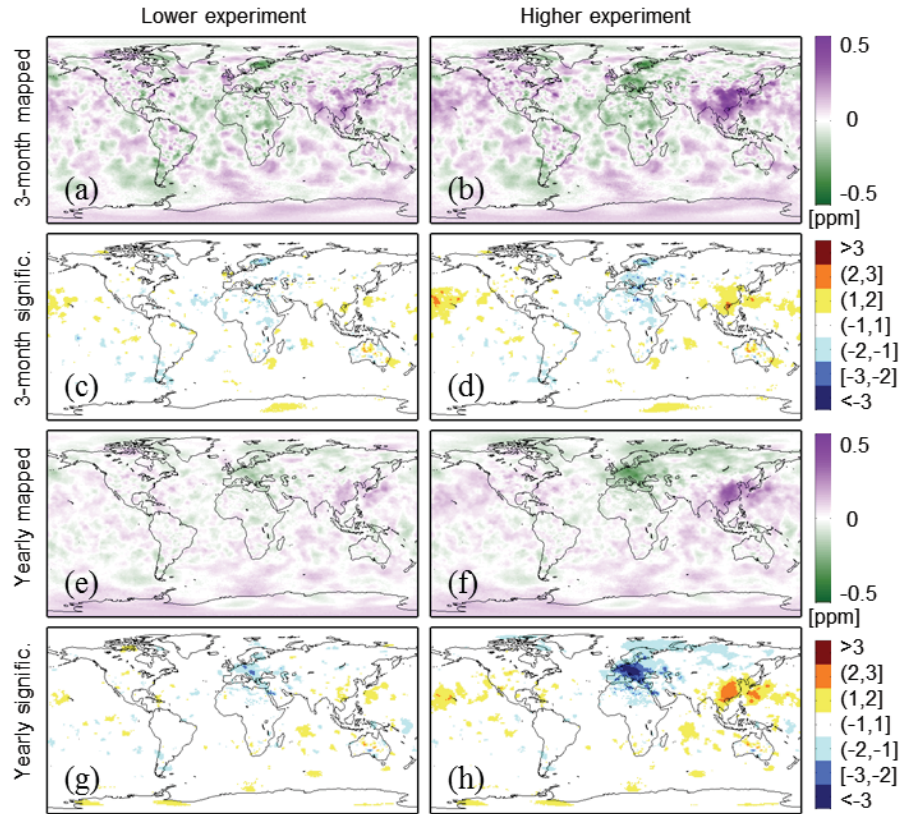


Figure 6: Results for the fossil fuel experiments for medium measurement noise. First row: 3-month mapped CO<sub>2</sub> signal (“3-month mapped”). Second row: Significance of the 3-month mapped CO<sub>2</sub> signal (“3-month signific.”). Third row: Yearly mapped CO<sub>2</sub> signal (“Yearly mapped”). Fourth row: Significance of the yearly mapped CO<sub>2</sub> signal (“Yearly signific.”). The mapped signal is the difference between the mapped perturbation CO<sub>2</sub> concentration and the mapped baseline CO<sub>2</sub> concentration. The significance is the mapped signal divided by the uncertainty of the mapped signal. The values are discretized for improved visualization. Yellow, orange and dark red (light, medium and dark blue) represent areas where the mapped perturbation concentration is larger (smaller) than the mapped baseline concentration by more than one, two or three standard deviations, respectively, of the uncertainty of the mapped signal. The 3-month period is August through September.

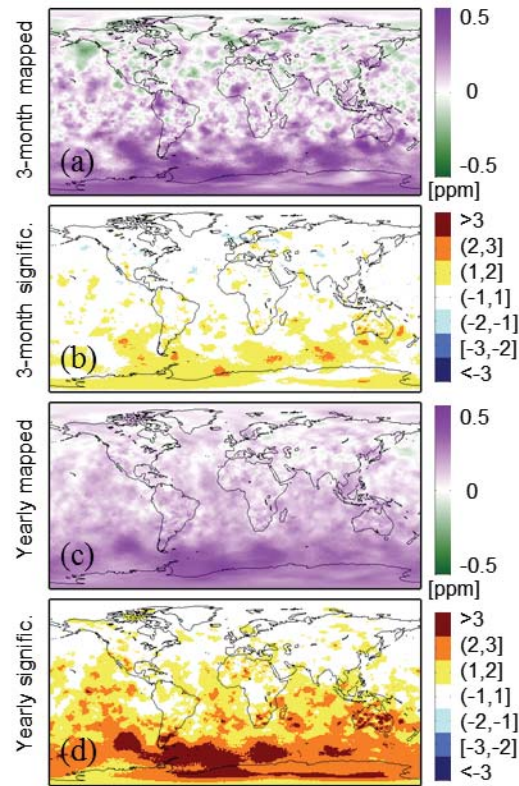


Figure 7: Results for the Southern Ocean experiment for medium measurement noise. (a) 3-month mapped CO<sub>2</sub> signal (“3-month mapped”), (b) Significance of the 3-month mapped CO<sub>2</sub> signal (“3-month signific.”), (c) Yearly mapped CO<sub>2</sub> signal (“Yearly mapped”), and (d) Significance of the yearly mapped CO<sub>2</sub> signal (“Yearly signific.”). The mapped signal is the difference between the mapped perturbation CO<sub>2</sub> concentration and the mapped baseline CO<sub>2</sub> concentration. The significance is the mapped signal divided by the uncertainty of the mapped signal. The values are discretized for improved visualization. Yellow, orange and dark red (light, medium and dark blue) represent areas where the mapped perturbation concentration is larger (smaller) than the mapped baseline concentration by more than one, two or three standard deviations, respectively, of the uncertainty of the mapped signal. The 3-month period is April through June.